POZNAN UNIVERSITY OF TECHNOLOGY



EUROPEAN CREDIT TRANSFER AND ACCUMULATION SYSTEM (ECTS) pl. M. Skłodowskiej-Curie 5, 60-965 Poznań

COURSE DESCRIPTION CARD - SYLLABUS

Course name			
Control systems of UAV			
Course			
Field of study		Year/Semester	
Aviation and cosmonautics		2/3	
Area of study (specialization)		Profile of study	
Unmanned Aerial Vehicles		general academic	
Level of study		Course offered in	
Second-cycle studies		polish	
Form of study		Requirements	
full-time		elective	
		Year/Semester	
		2/3	
		Profile of study	
		general academic	
		Course offered in	
		polish	
		Requirements	
		elective	
Number of hours			
Lecture	Laboratory classes	Other (e.g. online)	
15	0	0	
Tutorials	Projects/seminars		
0	15		
Number of credit points			
2			
Lecturers			
Responsible for the course/lecturer:		Responsible for the course/lecturer:	
dr Jędrzej Łukasiewicz		Responsible for the course/lecturer:	
email: jedrzej.lukasiewicz@put.pc	znan.pl		
tel. 61 224 45 11			
Wydział Inzynierii Lądowej i Trans	portu		
ul. Piotrowo 3, 60-965 Poznan			
Prerequisites			
Knowledge:			
The student has a basic knowledg	e of the construction of	of unmanned aerial vehicles, physics in the field	
of first degree studies,			
SKIIIS:		· for an all a second by a line in a second second second	
The student is able to analyze con	ipiex processes: ident	ily and describe their component parts.	
Social competences:		aviana valas in it. The student is able to	
The student is able to cooperate in	n a group, assuming v	arious roles in it. The student is able to	

determine the priorities important in solving the tasks set before him. The student shows independence in solving problems, gaining and improving the acquired knowledge and skills.

Course objective

To acquaint students with issues related to the methods of controlling unmanned aerial vehicles

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Course-related learning outcomes

Knowledge

1. Has extended knowledge of the construction, piloting and possibilities of using unmanned aerial vehicles in various areas of human activity

2. Has detailed and structured knowledge in the field of risk management in unmanned operations with varying degrees of operator control

Skills

1. Is able to plan and perform a flight on an unmanned aerial vehicle, taking into account the availability of airspace, terrain obstacles, UAV capabilities and the type of flight

2. Can lead the process of designing an unmanned aircraft and its operation based on known components and flight physics

Social competence

is aware of the importance and understands the non-technical aspects and effects of engineering activities, including its impact on the environment, and the related responsibility for decisions
is able to properly define the priorities for the implementation of the task set by himself or others

Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows: Lecture: written test (open test and questions) Project: evaluation of the written paper Programme content

LECTURE:

- 1. Principles of electro-magnetic propagation
- 2. Sources of disturbances in the emission of electro-magnetic radiation
- 3. Positioning systems used in on-board UAV devices
- 4. Sources of errors in positioning systems
- 5. Eutonomic flights ground distance sensors and pressure sensors
- 6. Control software for UAV flights

Teaching methods

Informative (conventional) lecture (providing information in a structured way) - may be of a course (introductory) or monographic (specialist) character

Bibliography

Basic

1. Prawo i procedury lotnicze / Henryk Jafernik, Radosław Fellner, Gliwice, 2015

2. Ustawa prawo lotnicze

3. Globalny system pozycyjny GPS. Budowa, działanie, zastosowanie, Janusz Narkiewicz Additional



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Breakdown of average student's workload

	Hours	ECTS
Total workload	50	2,0
Classes requiring direct contact with the teacher	30	1,0
Student's own work (literature studies, preparation for test,	20	1,0
project preparation) ¹		

¹ delete or add other activities as appropriate